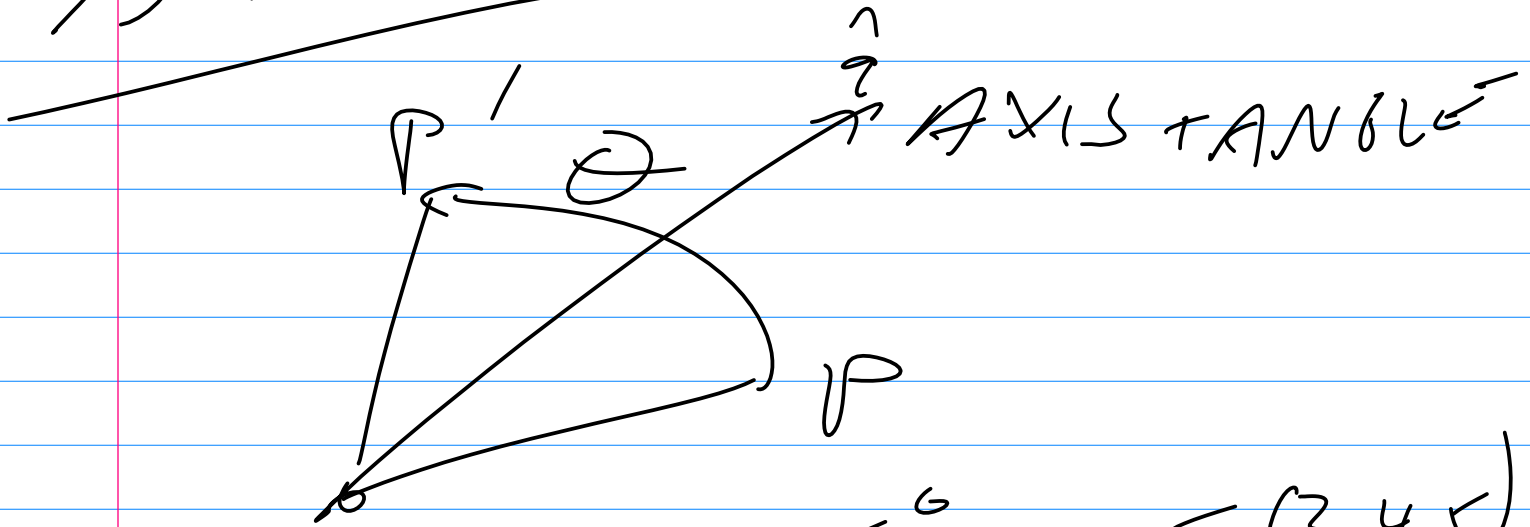


12/12/11

3D ROTATION



- INTUITIVE 45° ABOUT (3, 4, 5)
- ANIMATE IN MANY SMALL STEPS
1000 STEPS OF $\frac{45}{1000}^\circ$
ABOUT (3, 4, 5)

2 MATRIX FORM - COMBINE

3 EULER ANGLES
CONCEPTUALIZE

4 QUATERNIONS { MATCH HW IN GYROSCOPES ETC.
{ CAN COMBINE
{ AXIS + ANGLE

~~THERE MIGHT BE LITTLE~~
COMPUTATION QUESTIONS

Q) WHAT ARE AXIS ANGLE FOR THIS QUATERNION.

$$q = .7 + .7j$$

$$q = \cos \frac{\theta}{2} + \sin \frac{\theta}{2} (a_x i + a_y j + a_z k)$$

AXIS

$$= .7$$

$$\theta = \pm 45^\circ$$

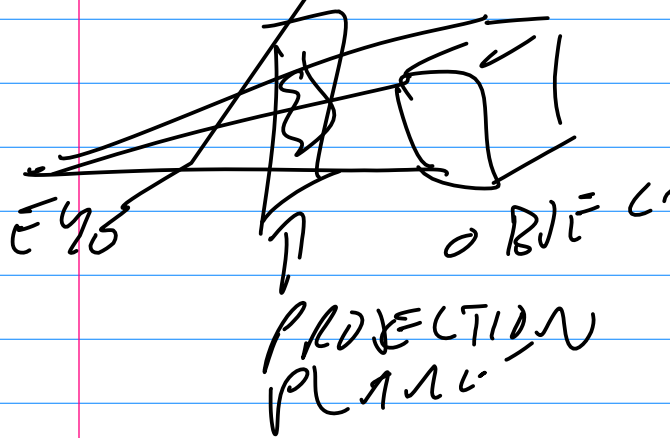
$$.7j = \sin \frac{\theta}{2} \text{ AXIS}$$

$$\text{AXIS} = (0, 1, 0)$$

$$\text{OR } (0, -1, 0)$$

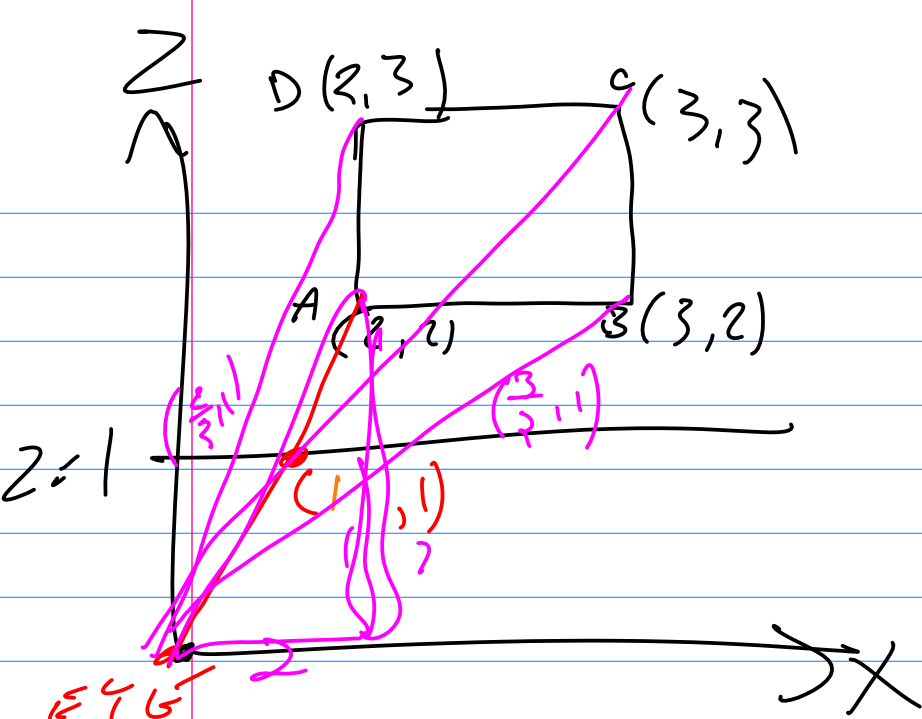
VIEW NORMALIZATION 3

PERSPECTIVE
PROJECTION

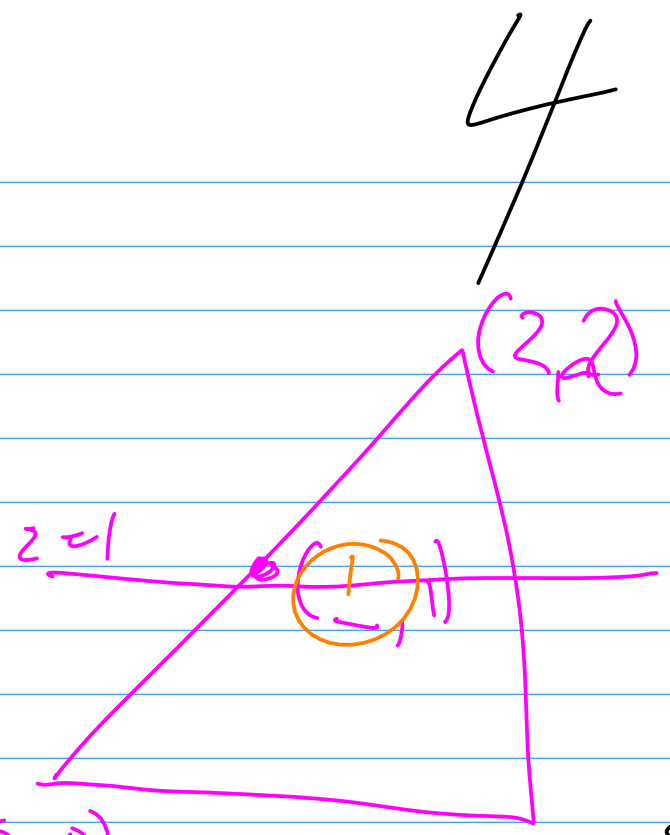


TO DISTORT THE
OBJECT SO
THAT THE
DISTORTED
OBJECT CAN
BE PARALLEL PRO-
JECTED

THE RESULTING IMAGE IS SAME



EYE CENTER OF PROJECTION



$(x, 2) \rightarrow (\frac{x}{2}, 1)$ $(0, 0)$

- W A(2,2) → A'(1,1)
- B(3,2) → B'(\frac{3}{2}, 1)
- C(3,3) → C'(1,1)
- D(2,3) → D'(\frac{2}{3}, 1)

PERSPECTIVE PROJECTION

DISTORTED SQUARE

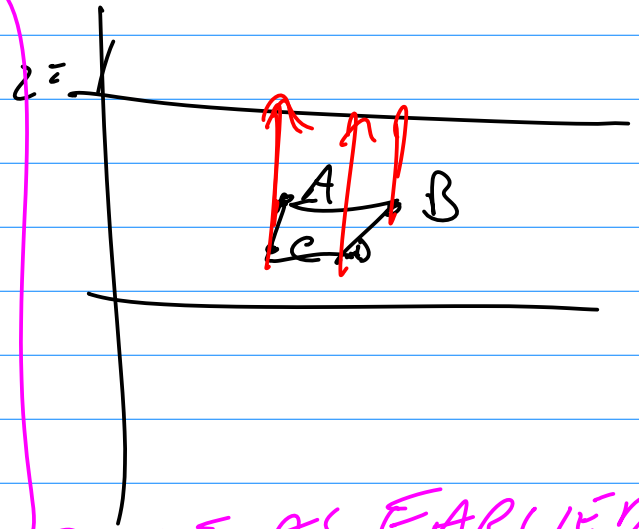
5

$$A(1, \frac{1}{2}) \rightarrow (1, 1)$$

$$B(\frac{3}{2}, \frac{1}{2}) \rightarrow (\frac{3}{2}, 1)$$

$$C(1, \frac{1}{3}) \rightarrow (1, 1)$$

$$D(\frac{2}{3}, \frac{1}{3}) \rightarrow (\frac{2}{3}, 1)$$



SAME AS EARLIER CASE

NOW DO PARALLEL PROJECTION

$$(X, Z) \rightarrow (X, 1)$$

HOMOGENEOUS COORDS 6

$$3D \ (X_H, Y_H, Z_H, W) \rightarrow \left(\frac{X_H}{W}, \frac{Y_H}{W}, \frac{Z_H}{W} \right)$$

$$\underbrace{(1, 2, 3, 4)}_{\text{HOMOG}} \rightarrow \underbrace{\left(\frac{1}{4}, \frac{2}{4}, \frac{3}{4} \right)}_{\text{CARTES}}$$

$W=0 \rightarrow$ POINT AT INFINITY

- TRANSLATION CAN BE A MATRIX
MULTIPLY

TRANSLATE BY $(3, 4, 5)$

$$\begin{pmatrix} 1 & 0 & 0 & 3 \\ 0 & 1 & 0 & 4 \\ 0 & 0 & 1 & 5 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \\ 3 \\ 1 \end{pmatrix} = \begin{pmatrix} 4 \\ 6 \\ 8 \\ 1 \end{pmatrix}$$

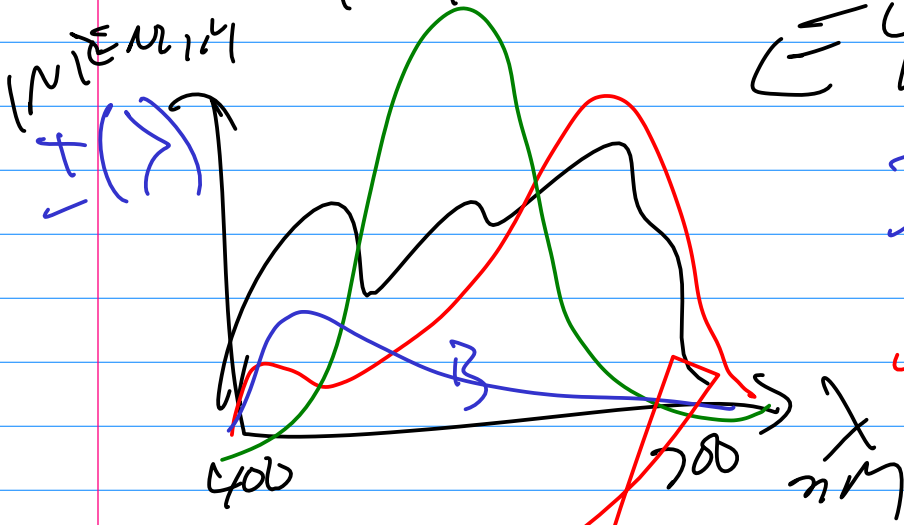
$(1, 2, 3)$ TRANSLATED BY $(3, 4, 5)$
IS $(4, 6, 8)$

COLORS

7

TRISTIMULUS

R, G, B RECEPTORS IN EYE



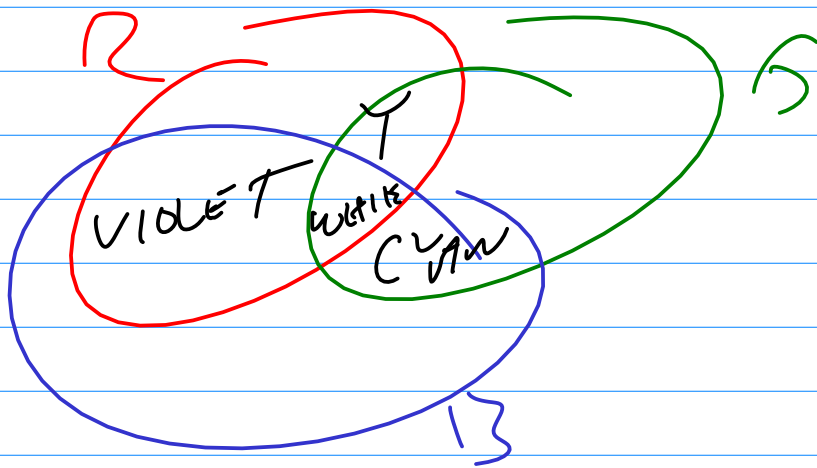
$$I_B = \int I(\lambda) B(\lambda) d\lambda$$

$$I_R = \int I(\lambda) R(\lambda) d\lambda$$

ADDITIVE MODEL

- SPOTLIGHT

BLACK BACKGROUND



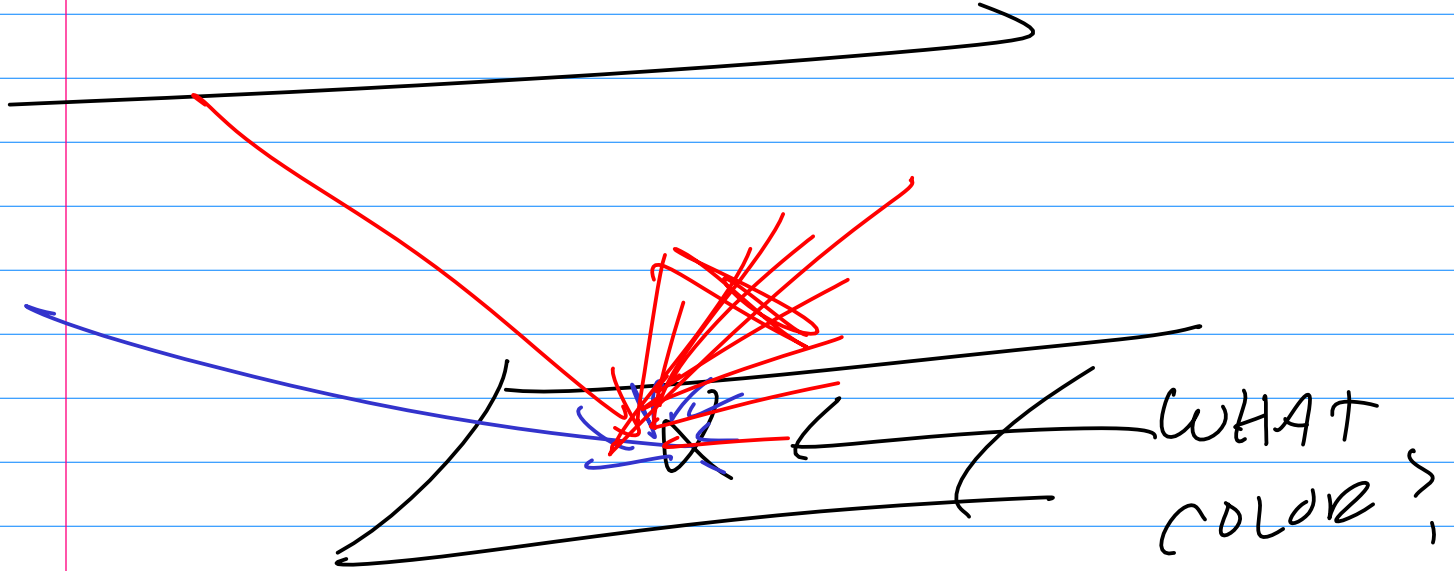
SUBTRACTIVE

INK ON PAPER,

WHITE BACKGROUND -

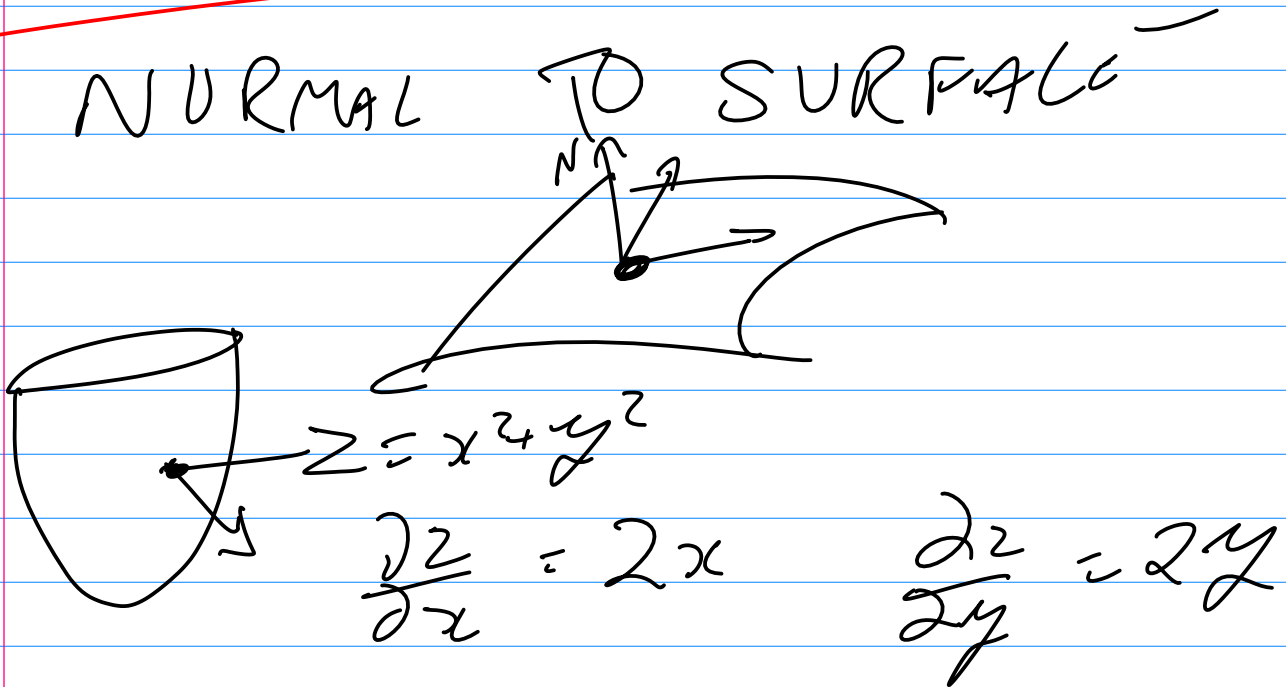
PHONB LIGHTING

8



AMBIENT + DIFFUSE + SPECULAR
+ EMITTED

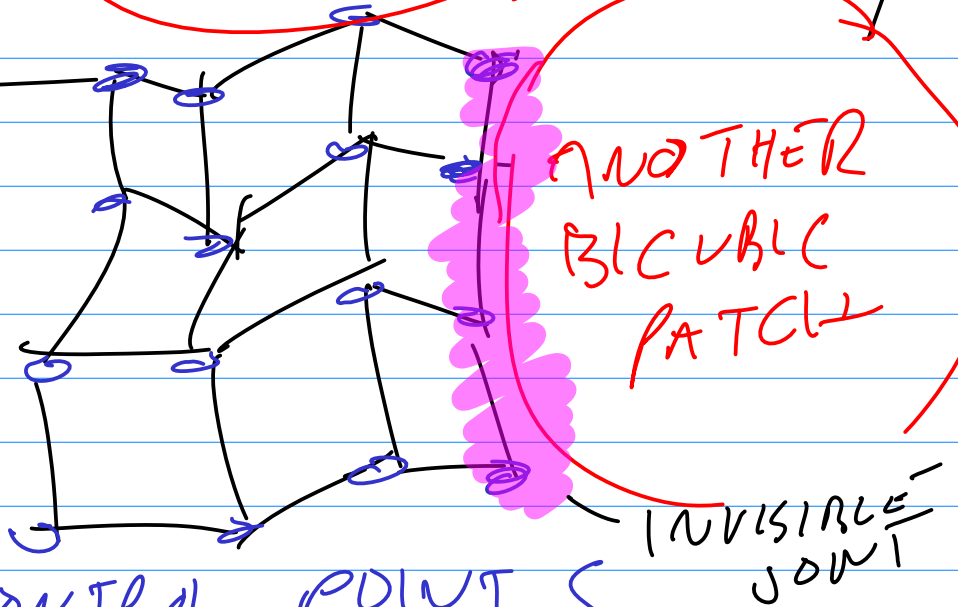
NORMAL TO SURFACE



FOR IMPLICIT SURFACE, ∇f IS NORMAL. $x^2 + y^2 + z^2 - 1 = 0$

MESHING

ANOTHER



4x4 CONTROL POINTS

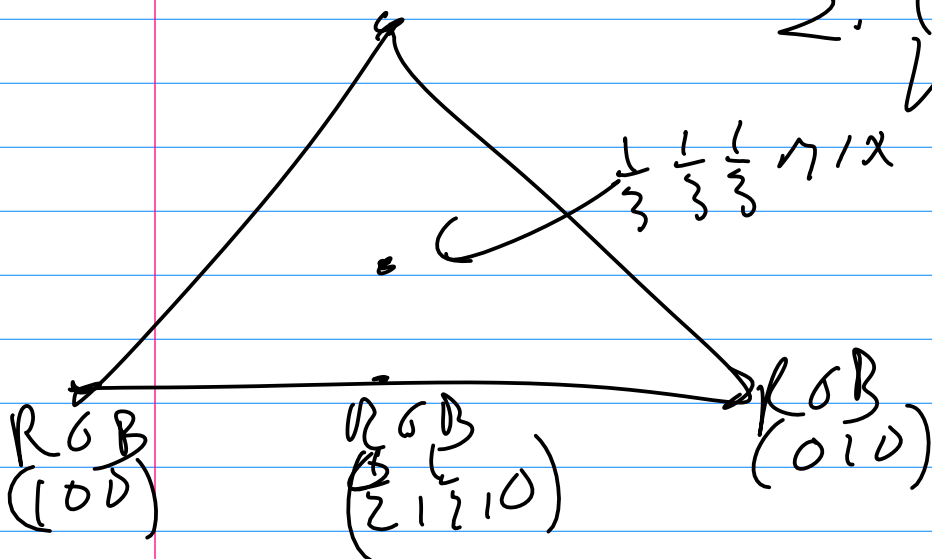
INVISIBLE JOINT

- FIND A SMOOTH SURFACE FROM CONTROL GRID.
- o BEZIER SURFACE

4 QUALITY LEVELS FOR

SHADING

1. 1 COLOR
 2. INTERPOLATE VERTEX COLORS
- MIX OF 3 VERTICES



3rd QUALITY LEVEL

USER SPECIFIES SURFACE

NORMALS @ VERTICES

OPENGL FINDS COLORS

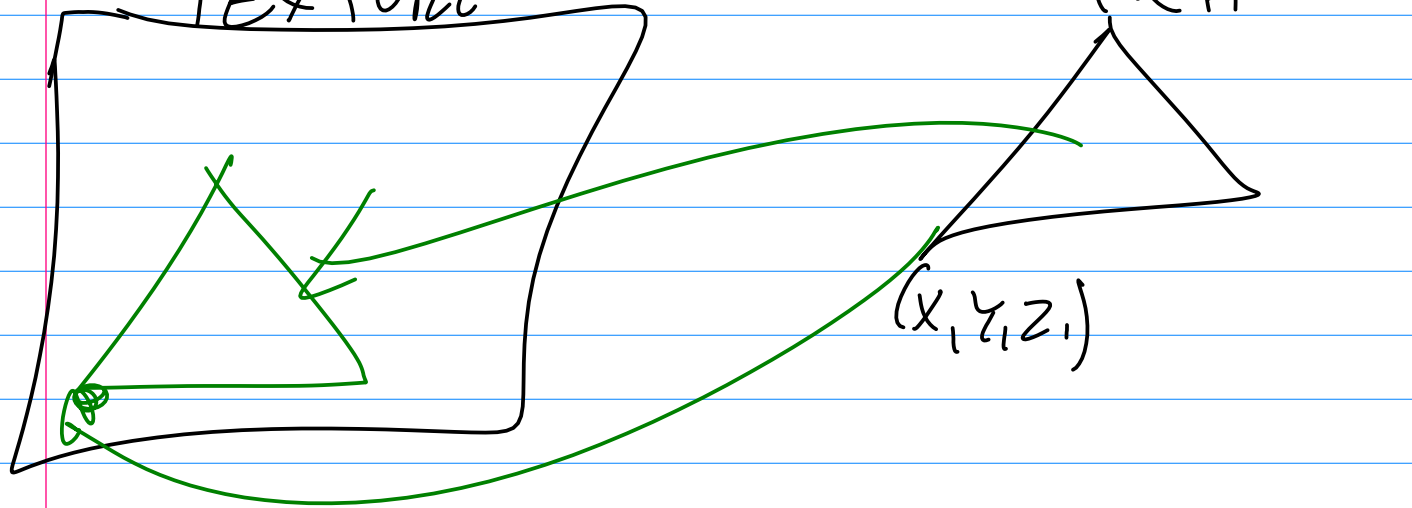
VERTICES + INTERPOLATES

COLOR

↳ INTERPOLATE NORMALS +
COMPUTE COLOR PER PIXEL

- ONLY #4 CAN PRODUCE A
HIGHLIGHT INSIDE TRIANGLE.

TEXTURE MAP



PIPELINES AKA SHADERS

