

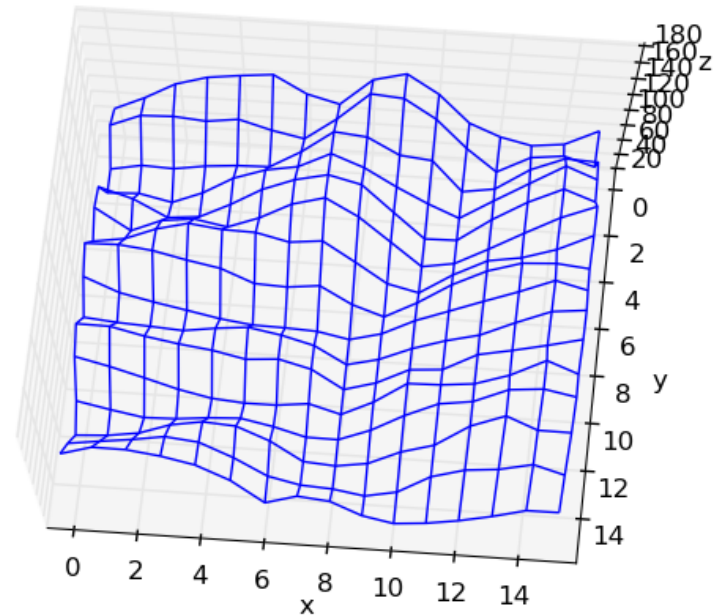
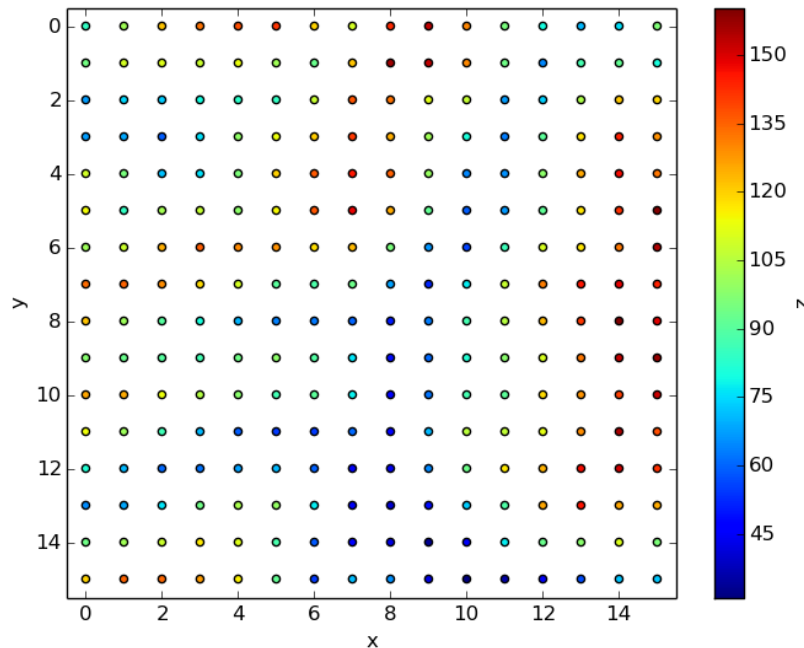
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CUNY Graduate Center
New York, NY*

Computing approximate horizons on a GPU

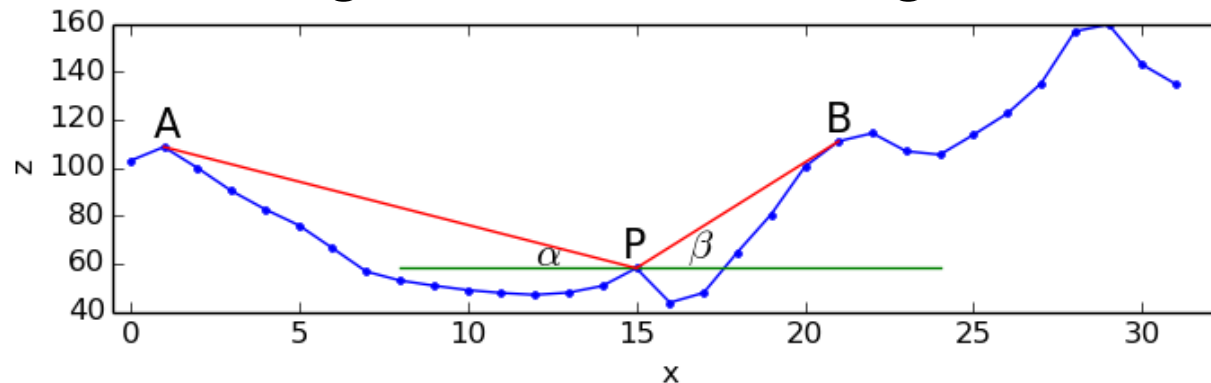
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Introduction

- Digital Elevation Model (DEM)



- Horizon: largest elevation angle

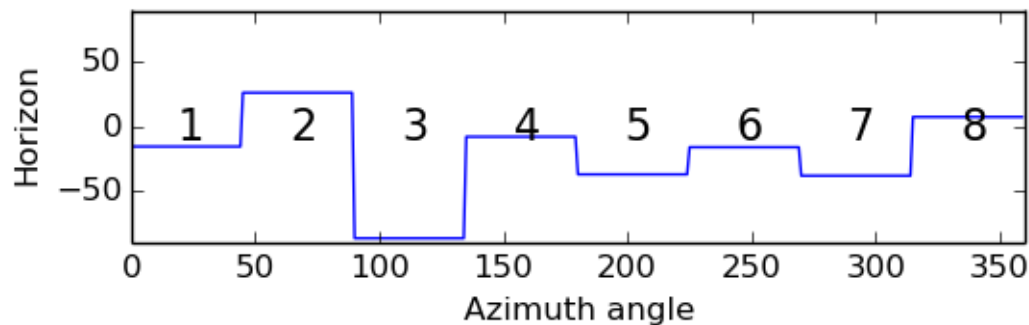
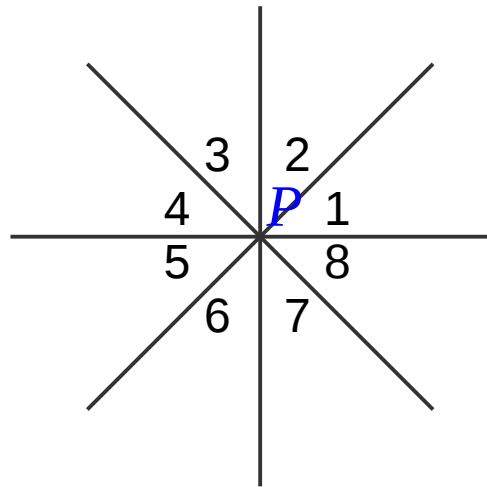


References

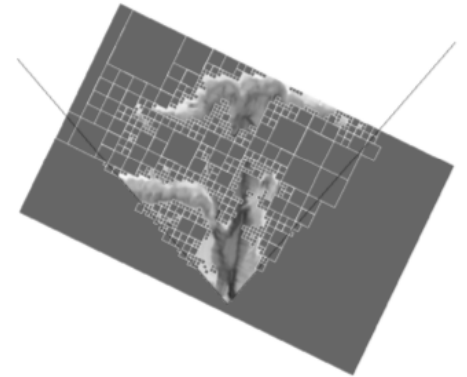
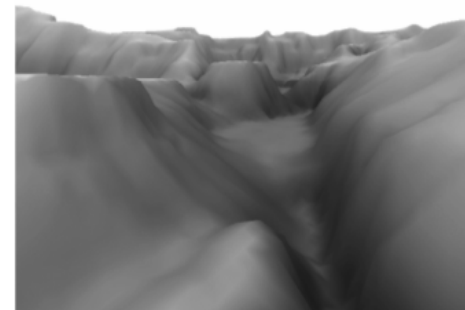
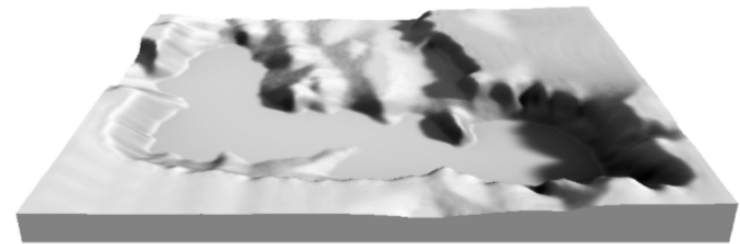
- [Ste98] A. J. Stewart. Fast horizon computation at all points of a terrain with visibility and shading applications. *IEEE Transactions on Visualization and Computer Graphics*, 4(1):82–93, Mar. 1998.
- [TRZ11] S. Tabik, L. F. Romero, and E. L. Zapata. High-performance three-horizon composition algorithm for large-scale terrains. *International Journal of Geographical Information Science*, 25(4):541–555, Apr. 2011.
- [BH86] J. Barnes and P. Hut. A hierarchical $O(N \log N)$ force-calculation algorithm. *Nature*, 324:446–449, Dec. 1986.

Motivation

- Approximate horizon: constant in each sector



- Applications: shading, visibility [Ste98], solar irradiance [TRZ11]



Motivation

- Stewart's algorithm: $O(sn\log^2(n))$
 - s sectors and n points
 - Approximate the horizon by the largest elevation angle in each sector
 - Parallel for the sectors and sequential for each sector
- Tabik et al.'s algorithm: dividing a terrain into blocks and using Stewart's algorithm
 - Compute “near” horizons for each block
 - Compute “far” horizons on a lower-resolution terrain
 - Parallel for the blocks and the sectors of a block



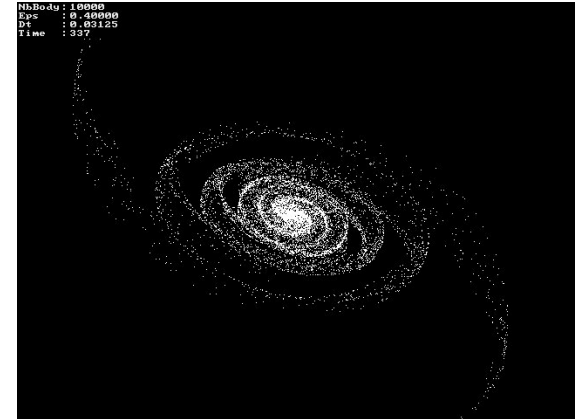
(a) New (64 sectors)



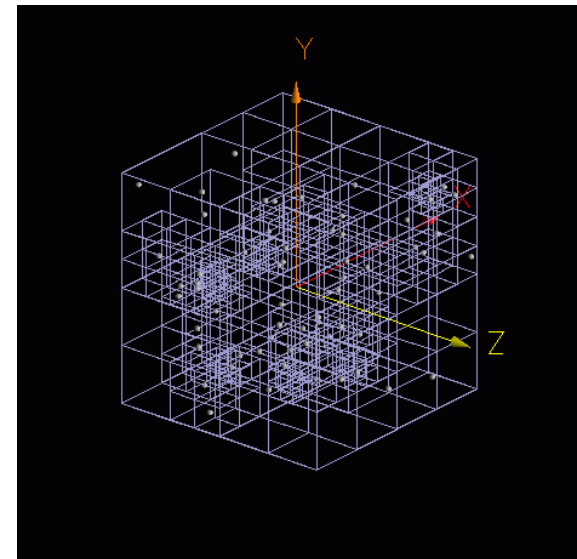
(d) CMS (64 sectors)

Motivation

- Barnes-Hut algorithm: $O(n \log(n))$
 - N-body simulation
 - Divide the space in an octree and store the center of mass and total mass in each internal node
 - Recursively traverse the tree to approximate the gravitational force on a body
 - Treat an internal node as a single body if $w/d < \theta$
 - w : width of the node
 - d : distance between the body and the node's center of mass



<http://insidehpc.com/2015/05/direct-n-body-simulation/>



GPU-friendly algorithms

- Brute-force algorithm: $O(n^2)$

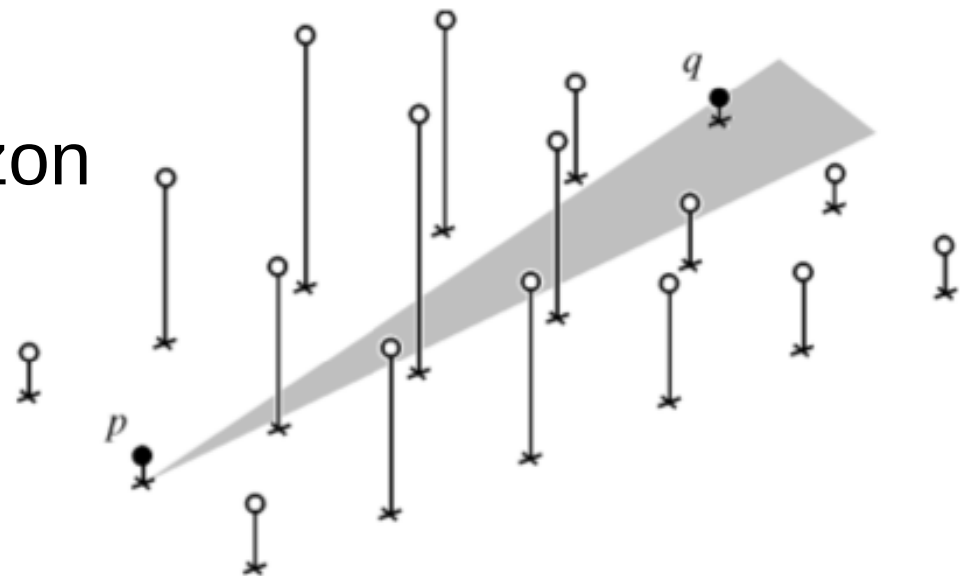
foreach point p **do**

foreach point q **do**

 find the sector s of p containing q ;

 update the horizon of p in s using q ;

- Narrow sectors [Ste98]
 - Underestimate the horizon



GPU-friendly algorithms

- Narrow sectors
 - Stewart's solution: checking about $s/2\pi$ bordering points on each side
 - Our solution: checking $s/2\pi$ points along the bisector

- Brute-force algorithm

foreach point p **do**

foreach sector s **do**

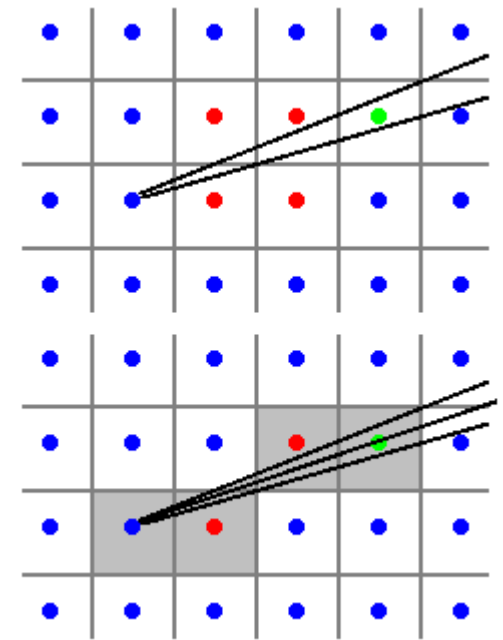
foreach point q of a few points along the bisector **do**

 update the horizon of p in s using q ;

foreach point q **do**

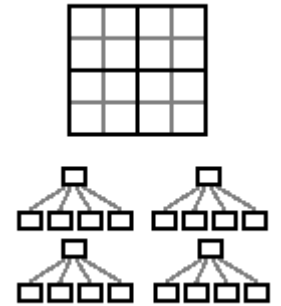
 find the sector s of p containing q ;

 update the horizon of p in s using q ;



GPU-friendly algorithms

- Quadtree-forest algorithm: $O(n \log(n))$
 - Like a 2D Barnes-Hut algorithm
 - Divide a terrain into blocks and build a largest-value quadtree for each block
 - Recursively traverses each quadtree to compute a horizon
 - Use a fixed-sized stack to simulate recursion on the GPU
 - Use a quadtree-forest instead of a quadtree
 - First few levels of a quadtree are not treated as points
 - Higher trees require a larger stack and more stack operations



GPU-friendly algorithms

- Quadtree-forest algorithm

divide the terrain into blocks and build a quadtree for each block;

foreach point p **do**

foreach sector s **do**

foreach point q of a few points along the bisector **do**

 update the horizon of p in s using q ;

foreach quadtree t **do**

 push the root of t on stack;

while the stack is not empty **do**

 pull a node n from stack;

foreach child c of n **do**

if c is not a leaf and $w/d > \theta$ **then**

 push c on stack;

else

 find the sector s of p containing c ;

 update the horizon of p in s using c ;

if n is not a leaf and $w/d > \theta$ **then**

foreach child c of n **do**

 push c on stack;

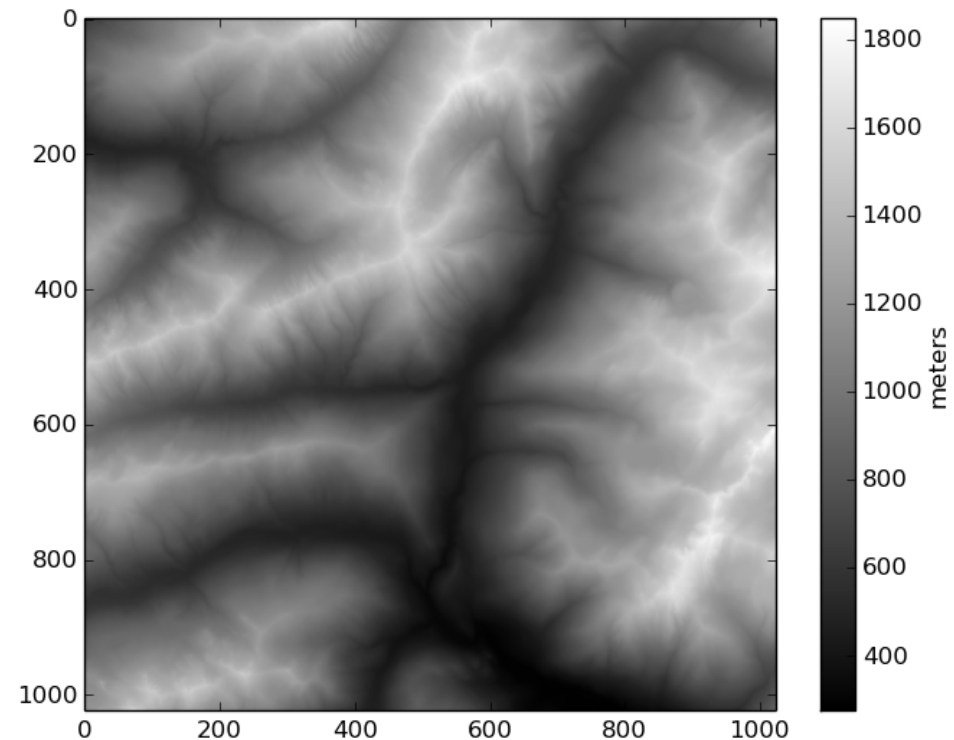
else

 find the sector s of p containing n ;

 update the horizon p in s using n ;

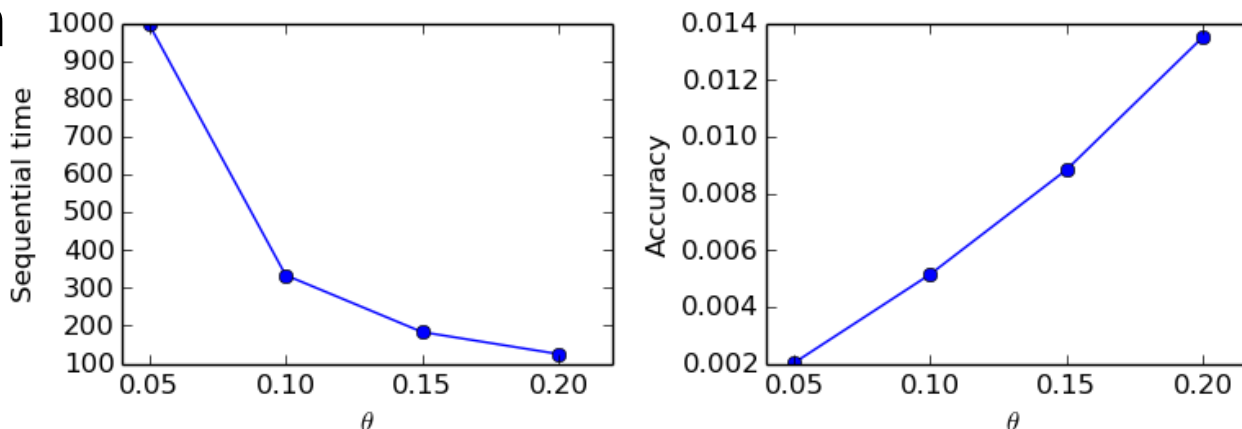
Results

- Implementations
 - Sequential programs on CPU
 - CUDA programs on GPU
- Hardware
 - Intel Xeon E5-2660 v4 CPU
 - NVIDIA GeForce GTX 1080 GPU
- Dataset: 1024x1024 DEM
 - 10-meter resolution
 - [274.7, 1846.8]-meter range
 - 64 sectors

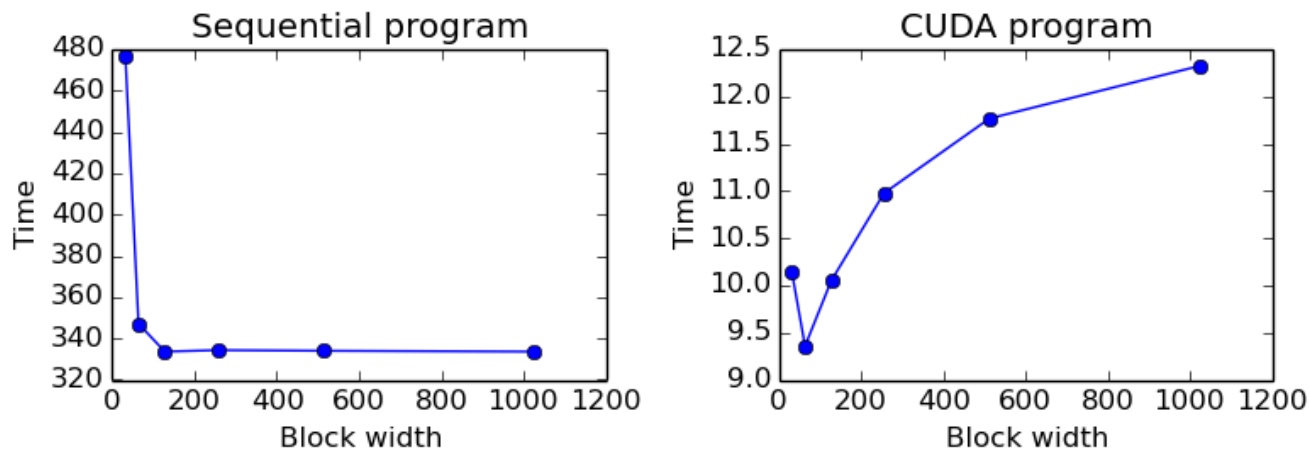


Results

- θ , running time, and accuracy of the quadtree-forest algorithm



- Block width and running time of the quadtree-forest algorithm ($\theta = 0.1$)



Results

- Running time and relative speedup of the programs
 - Quadtree-forest algorithm: $\theta = 0.1$
 - Sequential program: block width = 1024
 - CUDA program: block width = 64

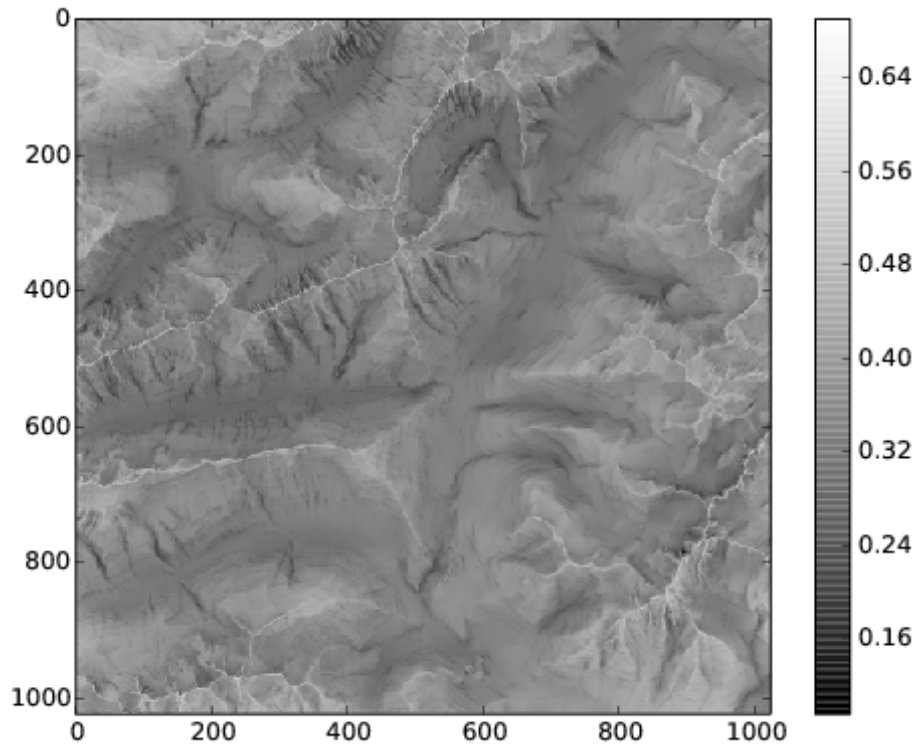
Algorithm	Sequential time	CUDA time	Speedup
Brute force	55278	984	56
Quadtree forest	334	9	36

Conclusions

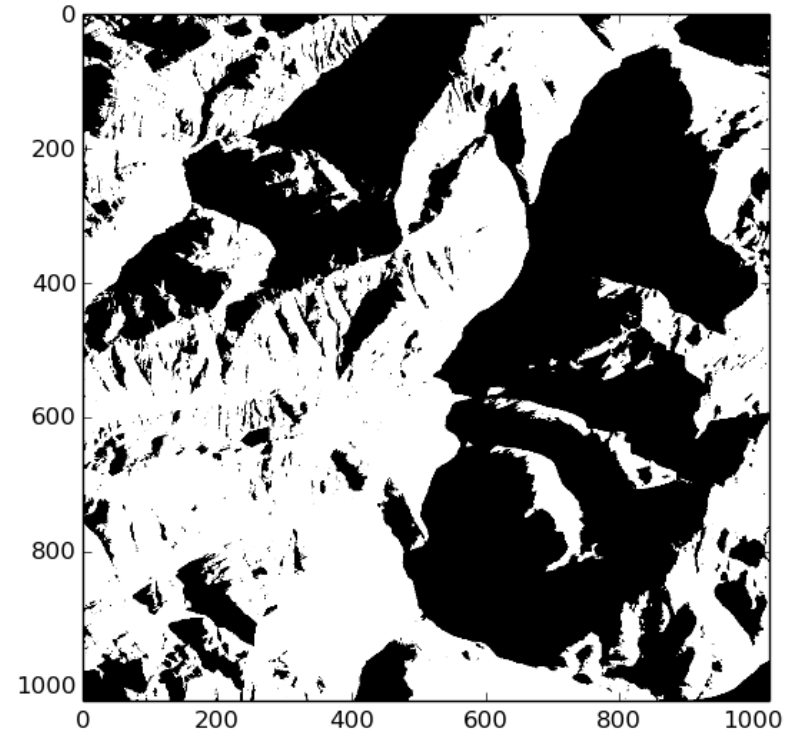
- Conclusions
 - The quadtree-forest algorithm is asymptotically faster and more suitable for the GPU
 - The result of the quadtree-forest algorithm is very close to that of the brute-force algorithm
- Future work
 - $O(n)$ algorithm?
 - W. Dehnen. A hierarchical $O(N)$ force-calculation algorithm. *Journal of Computational Physics*, 179(1):27–42, Jun. 2002.
 - Applications of approximate horizons

Thank you

- Visible sky area



- Casting shadows



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