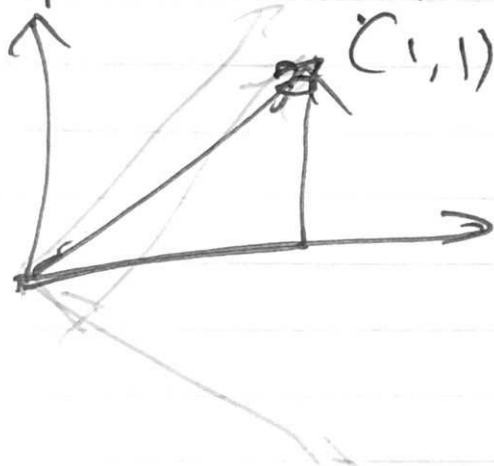


C4 2/10/20 P1

PS2

DIFFERENT BASIS SETS



$$H = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 2 \\ 0 \end{pmatrix}$$

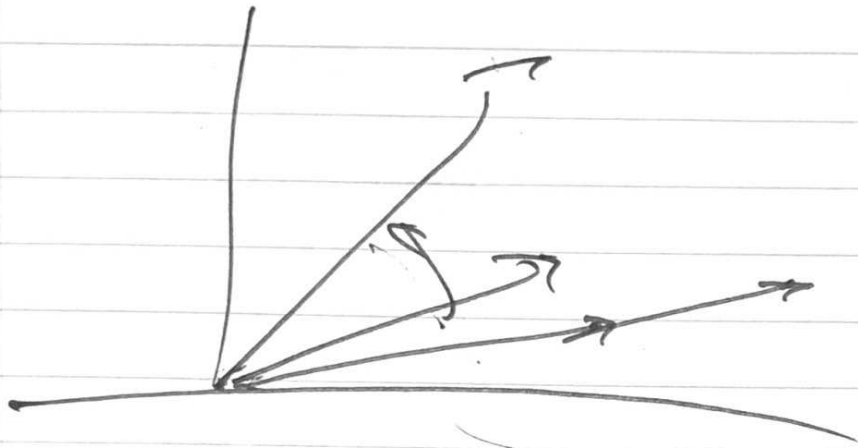
TRANSITION MATRIX

VECTOR SPACE  $u_1 + u_2$

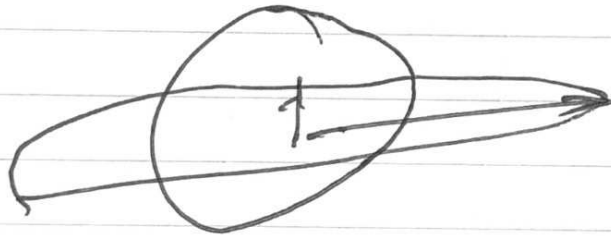
+ INNER } PRODUCT  
DOT }

$$\left\langle \begin{pmatrix} 4+2u \\ 3+4u \end{pmatrix}, \begin{pmatrix} 5+6u \\ 2+8u \end{pmatrix} \right\rangle$$

$$(1-2u)(5+6u) + (3-4u)(2+8u)$$



2



EIGENVECTORS : AXES  
 VALUES : HOW LENGTH  
 SCALE,

HERMETIAN

$$\begin{bmatrix} 1 & 3-4i \\ 3+4i & 2 \end{bmatrix}$$

UNITARY:

ROTATION  
 PRESERVES DISTANCE.

P91 3.2.2.

PROBABILITY OF STATE

TRANSITION IS NORM<sup>SQUARED</sup> OF LABEL ON ARC.

$L = \frac{1}{\sqrt{2}} \quad P = \frac{1}{\sqrt{2}}$

---

EX 3.3.1

FOR DETERMINISTIC DOUBLY STOCHASTIC MATRIX

$\sum_i a_{ij} = 1 \quad \text{ETC.}$

FOR QUANTUM  $\sum_n |a_{ij}|^2 = 1$

$\begin{pmatrix} \cos \theta \\ \sin \theta \\ 0 \end{pmatrix} \begin{pmatrix} \cos^2 \theta \\ \sin^2 \theta \\ 0 \end{pmatrix} \begin{matrix} \uparrow \\ \text{norm.} \\ \Sigma = 1 \end{matrix}$

WEIGHT

$$\frac{1}{\sqrt{2}}$$

$$P = \frac{1}{2}$$

4

$$-\frac{x^0}{\sqrt{2}}$$

$$P = \frac{1}{2}$$

EX 3.3.2

$$T=0 \quad \rho = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$T=1 \quad \rho = \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix}$$

~~T=2 GOES TO 0~~  $\frac{1}{\sqrt{2}} \frac{1}{\sqrt{2}} = \frac{1}{2}$

T=2 STATE IS  $\begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$

QUANTUM  
THINK

$$p(1 \rightarrow 3) = \left( \frac{-1+i}{\sqrt{6}} \right) \left( \frac{-1-i}{\sqrt{6}} \right) = \frac{1}{3}$$

WEAT END

$Q_3 = \text{WEIGHT ON STATE 3}$

$$\frac{1}{\sqrt{2}} \left( \frac{-1+i}{\sqrt{6}} \right) = \frac{-1+i}{\sqrt{12}}$$

$$P(\text{STATE 3}) = \left( \frac{-1+i}{\sqrt{12}} \right) \left( \frac{-1-i}{\sqrt{12}} \right) = \frac{1}{6}$$

THAT'S SAME AS BEFORE.

NOW DO  $P(\text{STATE 5})$

$$Q_5 = \frac{1}{\sqrt{2}} \left( \frac{1-i}{\sqrt{6}} \right) + \frac{1}{\sqrt{2}} \left( \frac{-1+i}{\sqrt{6}} \right) = 0$$

DESTRUCTIVE INTERFERENCE

IN DETERMINISTIC CASE  $P \rightarrow 0$

6

## SEC 3.4 ASSEMBLING SYSTEMS

WE HAVE 2 SEPARATE 1 QBIT SYSTEMS

NOW CONSIDER THEM TOGETHER AS ONE SYSTEM

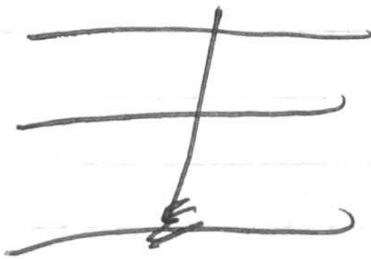
NO INTERACTIONS YET  
SIMPLE

THIS MOTIVATES TENSOR PRODUCT.

---

BLOCH SPHERE

$$N(0) \rightarrow \begin{pmatrix} a \\ b \end{pmatrix}$$



7

INFORMALLY HOW SEARCH  
WORKS:

$N$  QBITS  $\rightarrow 2^N$  STATES  
EACH STATE IS A POSSIBLE  
SOLUTION. INITIAL

WEIGHTS  $\begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \\ \vdots \end{pmatrix}$

APPLY OPERATOR THAT WILL  
CHANGE WEIGHT OF EACH  
STATE DEPENDING ON IF  
IT'S CORRECT ANSWER.

~~REPEAT~~ REPEAT EXPERIMENT,  
MEASURING AT DIFFERENT BASES,  
GET PROBABILISTIC SENSE  
OF SOLUTION.